FANUC Robot TR-5101A



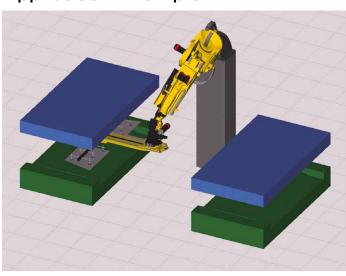
FEATURES

FANUC Robot TR-510iA is a high speed press tending robot.

- The combination of a 6-axis robot specially designed for press tending and a dedicated 2-axis tool, "Linear Press Tool" (LPT), achives high-speed transferring.
- The LPT has a work tilting function at the tip, which contributes to increasing the degree of freedom in press-line and mold design.
- The LPT with 130kg payload capacity can handle the transferring of large size workpieces.
- Two types of LPT are available: standard stroke suitable for press to press transferring and short stroke suitable for front/end of line.
- With the same control/teaching interface and maintenance method as other FANUC robots, this robot can be smoothly introduced to customers familiar with FANUC robots.
- Rack mount installation does not require a large scale mounting equipment such as a ceiling mount.

Linear Press Tool (LPT)

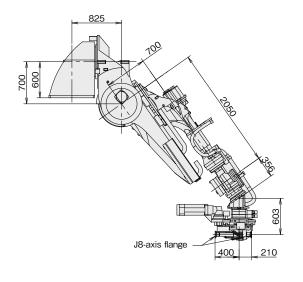
Application Example

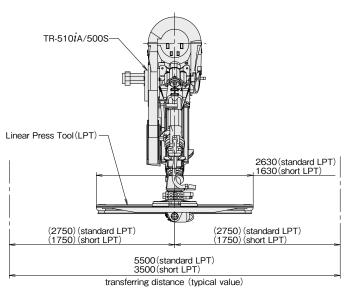


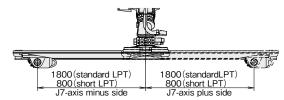
Press to press transferring

Outer Dimension

TR-510*i*A/500S







Specifications

Model		TR-510 <i>1</i> A/500S	
Linear Press Tool (LPT)		Standard	Short
Controlled axes		6-axes robot + 2-axes LPT (J1, J2, J3, J4, J5, J6, J7, J8)	
Transferring distance Note 1)		5500 mm	3500 mm
Installation		Rack mount	
Motion range (Maximum speed) Note 2)	J1 axis	180° (92°/s) 3.14 rad (1.61 rad/s)	
	J2 axis	148° (30°/s) 2.58 rad (0.52 rad/s)	
	J3 axis	1050 mm (1300 mm/s)	
	J4 axis	720° (70°/s) 12.6 rad (1.22 rad/s)	
	J5 axis	230° (100°/s) 4.01 rad (1.75 rad/s)	
	J6 axis	720° (55°/s) 12.6 rad (0.96 rad/s)	
	J7 axis	±1800 mm (7000 mm/s)	±800 mm (7000 mm/s)
	J8 axis	40° (120°/s) 0.70 rad (2.10 rad/s)	
Max. load capacity of Linear Press Tool		130 kg	
Max. load capacity on J3 casing		25 kg	
Mass Note 3)		4350 kg	4310 kg
Installation envirionment		Ambient temperature : 0 to 45°C Ambient humidity : Normally 75%RH or less (No dew, nor frost allowed) Short term 95%RH or less (within one month) Vibration acceleration : 4.9m/s² (0.5G) or less	

This is a typical value, and the applicable range changes depending on the load conditions. Note 1)

During short distance motions, the axis speed may not reach the maximum value stated. Note 2)

With LPT, without controller.

FANUC CORPORATION

• Headquarters Oshino-mura, Yamanashi 401-0597, Japan Phone: (+81)555-84-5555 https://www.fanuc.co.jp/

 Overseas Affiliated Companies Overseas Affiliated Companies
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FANUC OCEANIA PTY., LIMITED
FANUC SOLITH AFRICA (PROPRIETARY) LIMITED FANUC SOUTH AFRICA (PROPRIETARY) LIMITED

Phone: (+1)248-377-7000 Phone: (+352)727777-1 Phone: (+86)21-5032-7700 Phone: (+88)21-5278-1200 Phone: (+88)4-2359-0522 Phone: (+68)4-2359-0522 Phone: (+66)5567-8566 Phone: (+66)2714-6111 Phone: (+66)23-14-6111 Phone: (+66)21-4584-7285 Phone: (+61)2-8822-4600 Phone: (+61)2-8822-4600 Phone: (+27)11-392-3610

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