FANUC Robot CR-351A



FEATURES

FANUC Robot CR-35iA is a 35 kg payload collaborative robot that can work without safety fences.

Collaborative Operation

- This robot and a human operator can work together within a shared workspace without safety fences.
- This robot can work in cooperation with a human operator. (example: heavy workpiece transfer, parts assembling)
- With Hand Guidance(option), intuitive operation and easy teaching are possible.

Safety Function

- This robot stops safely when it touches a human operator.
- Safe and gentle looking green soft cover reduces an impact force and prevents a human operator from being pinched.
- CR-35iA is certified to meet the requirements of international standard ISO 10218-1.

Intelligence and High Reliability

- Latest intelligent functions such as iRVision (Integrated vision) are available.
- This robot is designed with the same high reliability as conventional robots.

Application Example



Parts assembly by collaborative operation



Workpiece transfer with Hand Guidance

Operating space





Specifications

lodel	CR-351A
	Articulated Type
	6 axes (J1, J2, J3, J4, J5, J6)
	1813 mm
	Floor
J1 axis rotation	340° / 370°(Option) 5.93 rad / 6.46 rad(Option)
J2 axis rotation	165° 2.88 rad
J3 axis rotation	258° 4.50 rad
J4 axis wrist rotation	400° 6.98 rad
J5 axis wrist swing	220° 3.84 rad
J6 axis wrist rotation	900° 15.71 rad
y at wrist	35 kg
y on J3 casing	2 kg
Note 1, Note 2)	750 mm/s
J4 axis	110 N·m
J5 axis	110 N·m
J6 axis	60 N⋅m
J4 axis	4.00 kg⋅m²
Allowable load inertia at wrist	4.00 kg⋅m²
J6 axis	1.50 kg⋅m²
	Electric servo drive by AC servo motor
e 3)	±0.03 mm
	990 kg
nment	Ambient temperature : 0 to 45°C Ambient humidity : Normally 75 %RH or less (No dew nor frost allowed) Short time (within one month) Max.95%RH Vibration acceleration : 4.9 m/s² (0.5G) or less
	J2 axis rotation J3 axis rotation J4 axis wrist rotation J5 axis wrist swing J6 axis wrist rotation y at wrist y on J3 casing Note 1, Note 2) J4 axis J5 axis J6 axis J4 axis J5 axis at axis b axis b axis b axis b axis c 3)

Note 1) In case of short distance motion, the speed may not reach the maximum value stated. Note 2) It is necessary to set a motion speed according to risk assessment of system.

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Note 3) Compliant with ISO9283.

Note 4) Without controller.

FANUC CORPORATION

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